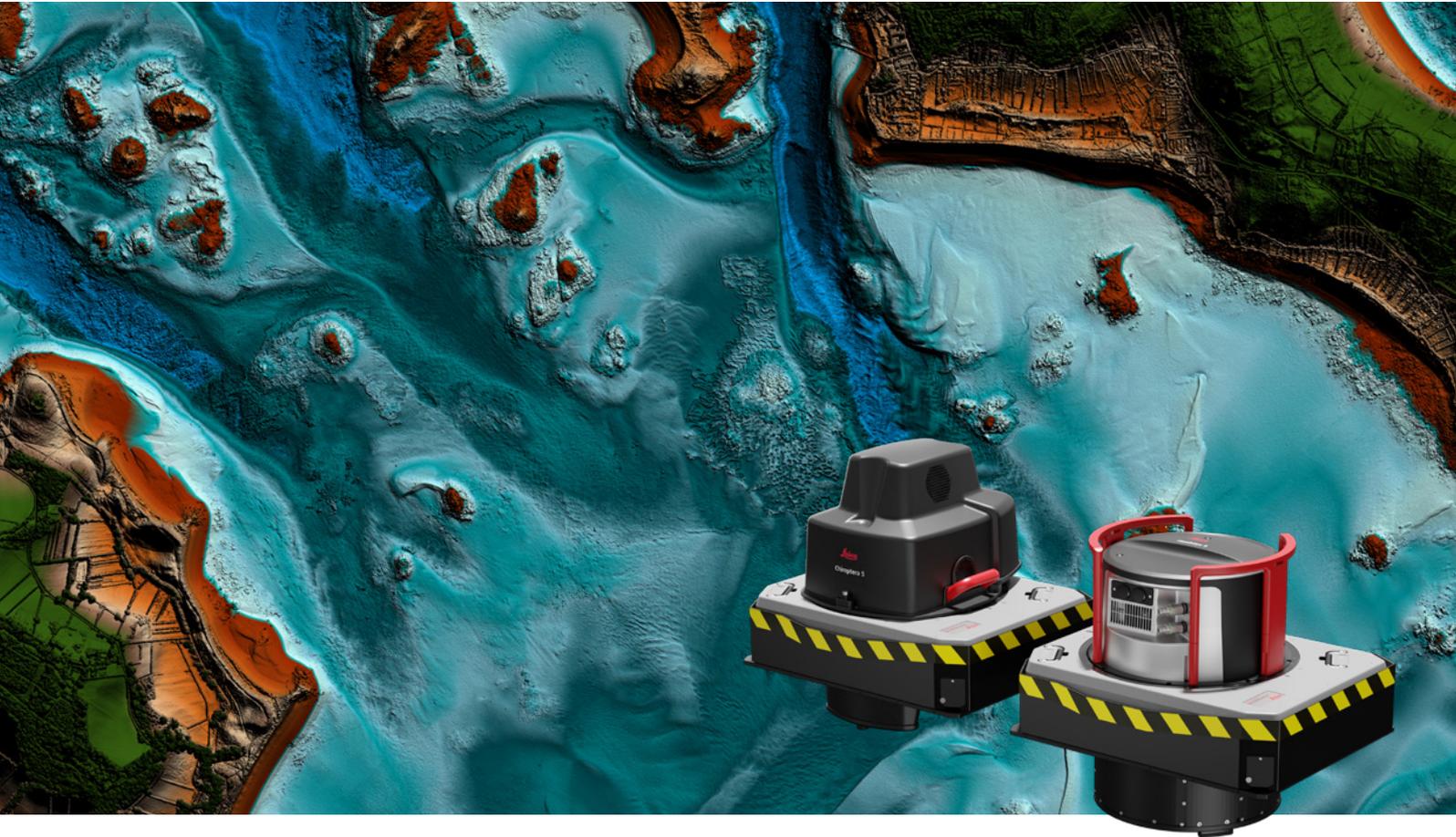


# Leica HawkEye-5

## Highest efficiency for deep bathymetric LiDAR surveys



### Superior productivity

Installed in the Leica PAV100 gyro-stabilised sensor mount, the Leica HawkEye-5 offers up to 25% higher flight efficiency compared to previous generations. The system captures data faster, allowing customers to reduce the operational costs, project time and carbon footprint of each mapping project.



### From land to deep ocean

Bundled with the Leica Chiroptera-5, the HawkEye-5 features three LiDAR sensors, one 4-band high-resolution camera and one QC camera. Each module is optimised for a specific task, allowing seamless acquisition of the highest quality data from land to deep ocean seafloor.



### High-performance workflow

The HawkEye-5 is supported by Leica Geosystems' integrated workflow. The Leica LiDAR Survey Studio (LSS) processing suite enables full waveform analysis, automatic data classification, and advanced turbid water enhancement to support multiple applications in all bathymetric channels.

- when it has to be **right**

**Leica**  
Geosystems

# Leica HawkEye-5 product specifications

## CHIROPTERA-5 SENSOR HEAD

<b>Consists of</b>	
1 x Chiroptera-5 bathymetric LiDAR unit	
1 x Chiroptera-5 topographic LiDAR unit	
1 x Leica RCD30 RGBN mid-format camera	
1 x RGB small format QA camera	
1 x IMU class 5, 500 Hz	
<b>Dimensions (l/w/h)</b>	480 / 510 / 640 mm
<b>Weight</b>	48 kg
Designed for installation in the Leica PAV100 mount	

## HAWKEYE-5 DEEP MODULE SENSOR HEAD

<b>Consists of</b>	
1 x HawkEye-5 bathy LiDAR unit	
1 x IMU class 5, 500 Hz	
<b>Dimensions (l/w/h)</b>	435/435/600 mm
<b>Weight</b>	53 Kg
Designed for installation in the Leica PAV100 mount	
<b>Typical data resolution <sup>1,2</sup></b>	
<b>Deep bathymetric data</b>	1 points/m <sup>2</sup>
<b>Shallow bathymetric data</b>	5 points/m <sup>2</sup>
<b>Topographic data</b>	Up to 12 points/m <sup>2</sup>
<b>RGB image</b>	5 cm GSD
<b>NIR image</b>	5 cm GSD

## HAWKEYE-5 / CHIROPTERA-5 SENSORS CONTROLLER UNIT

<b>Consisting of</b>	
1 x HE/CH-5 SCU, that controls and logs the bathymetric and topographic LiDAR scanners	
1 x Leica CC43 camera controller, that controls and logs the RCD30 camera, controls the Chiroptera-5 sensor head PAV stabilisation and includes a deeply coupled GNSS 4 x SSD removable mass memories	
<b>Dimensions (l/w/h)</b>	560 / 540 / 580 mm
<b>Weight</b>	57 Kg

## HAWKEYE-5 LASER COOLER UNIT

<b>Consist of</b>	
1 x HawkEye-5 laser cooler	
1 x Leica CC43 camera controller, that controls and logs the HawkEye-5 deep module sensor head PAV stabilisation and includes a deeply coupled GNSS 2 x SSD removable mass memories	
<b>Dimensions (l/w/h)</b>	560 / 540 / 580 mm
<b>Weight</b>	60 Kg

## HAWKEYE-5 PERIPHERALS

2 x Leica PAV 100 gyro stabilised sensor mount for high performance data acquisition (40 kg each)	
2 x Leica OC60 12.1" operators' consoles (3.2 kg each)	
1 x Leica PD 60 6.3" Pilot display, designed for installation in Cockpit (1.0 kg)	
1 x Leica IS40 stand for mounting the OC60's (8 kg)	
GPS antenna, cabling and safety controls (10-15 kg)	

## DEEP BATHYMETRIC LIDAR

<b>Laser wavelength</b>	515 nm
<b>Laser divergence</b>	7.5 mrad
<b>Bathymetric capture <sup>2</sup></b>	40 KHz, full waveform capture
<b>Depth penetration <sup>1,3,8</sup></b>	$D_{max} > 4.0/K_d @ \rho=15\% \text{ TBC}$
<b>Flying altitude</b>	400-600 m AGL nominal
<b>Ranging accuracy <sup>4</sup></b>	< 2 cm (1 $\sigma$ )
<b>Elevation accuracy <sup>1,3,5,6</sup></b>	$\sqrt{(0.3^2 + (0.013 \cdot d)^2)}$ m (2 $\sigma$ )
<b>Horizontal accuracy <sup>1,3,5,6</sup></b>	(2.0 + 0.075d) m (2 $\sigma$ )

## SHALLOW BATHYMETRIC LIDAR

<b>Laser wavelength</b>	515 nm
<b>Laser divergence</b>	4.75 mrad
<b>Bathymetric capture <sup>2</sup></b>	200 KHz, full waveform capture
<b>Depth penetration <sup>1,3</sup></b>	$D_{max} = 3.2/K_d @ \rho=15\%$ $D_{max} \approx 3.8/K_d @ \rho=60\%$
<b>Flying altitude</b>	400-600 m AGL nominal. Higher altitudes feasible
<b>Ranging accuracy <sup>4</sup></b>	< 1 cm (1 $\sigma$ )
<b>Elevation accuracy <sup>1,3,5,6</sup></b>	IHO special order
<b>Horizontal accuracy <sup>1,3,5,6</sup></b>	IHO special order

## TOPOGRAPHIC LIDAR

<b>Laser wavelength</b>	1.064 nm
<b>Laser divergence</b>	0.5 mrad
<b>Topographic capture</b>	Up to 500.000 KHz. Full waveform recording option at down-sampled rate's
<b>Flying altitude</b>	400 - 1.600 m AGL
<b>Ranging accuracy <sup>4</sup></b>	< 1 cm (1 $\sigma$ )
<b>Elevation accuracy <sup>1,5</sup></b>	< 5 cm (1 $\sigma$ )
<b>Horizontal accuracy <sup>1,5</sup></b>	< 15 cm (1 $\sigma$ )

## COMMON LIDAR SPECS

<b>Field of view</b>	$\pm 14^\circ$ front/back $\pm 20^\circ$ left/right
<b>Scan pattern</b>	Oblique front-back palmer scan pattern
<b>Scanner speed topo / shallow</b>	Up to 5.000 rpm (170 scans/s)
<b>Scanner speed deep</b>	Up to 3.000 rpm (100 scans/s)
<b>Swath width</b>	70% of AGL
<b>Intensity digitisation</b>	14 bit
<b>Sampling speed</b>	1.8 GHz
<b>Min vertical separation</b>	< 50 cm

## MID FORMAT MULTISPECTRAL CAMERA

<b>Type</b>	Leica RCD30
<b>Resolution</b>	80 MP (10.320 x 7.752 pixels)
<b>Motion compensation</b>	2-axis mechanical
<b>Spectral co-registered bands</b>	B: 440-520 nm G: 500-580 nm R: 570-650 nm NIR: 780-850 nm
<b>Frame rate</b>	1 fps
<b>Lens</b>	50 mm 53.8°FOV across track 41.8° FOV along track

## CHIROPTERA QA CAMERA

<b>Resolution</b>	5 MP (2.448 x 2.050 pixels)
<b>Spectral bands</b>	RGB
<b>Typical GSD <sup>1</sup></b>	25 cm

## INTEGRATED GNSS IMU SYSTEM

<b>IMU</b>	2 x SPAN CNU55-H, Class 5, 500 Hz
<b>GNSS</b>	NovAtel SPAN OEM7, 555 channel multi constellation, 10 Hz GNSS data rate
<b>Additional features</b>	Real-time deeply coupled solution for position and attitude at highest accuracies.
<b>Position RMS DGNSS</b>	Post-processed spec X,Y < 3-5 cm, Z < 5-7cm Post processed typical X,Y < 2-3 cm, Z < 3-5 cm

## ENVIRONMENTAL

Pressure	3.000 m operational, 5.000 m non-operational
Humidity	DO-160G, Section 6, Cat A
Operating temperature	0 to 30°C
Storage temperature	-10 to 50°C

## ELECTRICAL

Average power	< 2.000 W
Max peak power	< 2.800 W
Fuse on AC power	1x40 A + 1x50 A recommended @ 28 VDC

## SOFTWARE

Mission Planning	Leica MissionPro
Flight Navigation and Flight Operation	Leica FlightPro, Leica Chiroptera AOC
GNSS / INS trajectory processing	NovAtel Inertial Explorer
Image processing	Leica HxMap
Topo/Bathy LiDAR processing	Leica LiDAR Survey Studio (LSS)

## SENSOR MOUNT

Sensor mount	Leica PAV100 Stabilised sensor mount
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### Leica PAV100

The Leica PAV100 stabilises the sensor heads from aircraft pitch, yaw, and roll movements, allowing flying with less overlap between flight lines and significantly improving flight efficiency. The stabilisation prevents glitches between flight lines, rotates the camera images in the orientation of the flight direction, independent of side wind, for better image quality, and provides a more even distance between scan lines. The increased flight efficiency allows the capture of larger areas faster, reducing survey costs, reducing aircraft carbon footprint, reducing risk for the need for re-flights and increasing the total yearly area possible to collect with the sensor. This enables a higher return on sensor investment and delivers better data quality.

## STANDARDS

RTCA DO-160G, EUROCAE-14G, USA FCC Part 15, ISO 7137, EN/IEC 60825-1:2014, IHO S-44 Ed 6.0.

## EXPORT CONTROL

Subject to European export regulations EU 4 28/2009, classifications 6A008j. 3 (Hardware) and 6D002 (Software).

<sup>1</sup> Assumed 400 m AGL flight altitude, 65 m/s flight speed

<sup>2</sup> Using Leica proprietary 4x technology

<sup>3</sup>  $K_d$  is the water downwelling diffuse attenuation coefficient. Formula valid for  $0.1 < K_d < 0.4$ . Data is however captured both in clearer water  $K_d < 0.1$ , and significant more turbid water up to approximately  $K_d=1.0$ . Stated vertical and horizontal accuracies after calibration and registration using Leica Geosystems workflow and with assumed GNSS position error < 4.0 cm

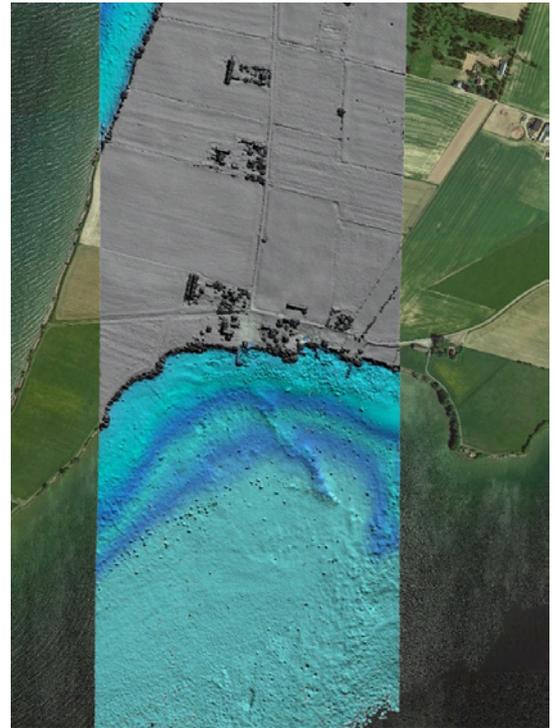
<sup>4</sup> In Leica test lab environment towards flat target

<sup>5</sup> Post processed data with GPS reference station within 30 km and under good satellite coverage conditions

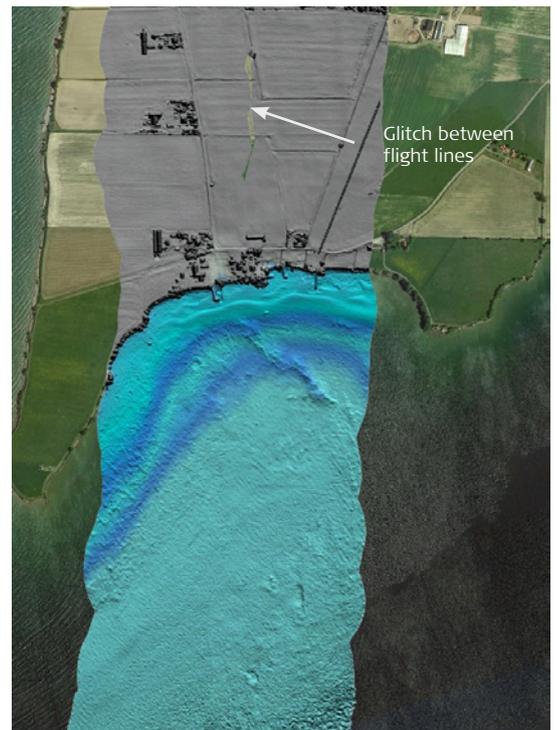
<sup>6</sup> Referenced to IHO S44 specification. Transformation errors between ellipsoid and chart datum (not measured by the system) assumed neglectable

<sup>7</sup> Object diffuse reflection assumed  $p=15\%$

<sup>8</sup> Final depth penetration specification to be confirmed, preliminary  $D_{max}=4.4/K_d @ p=15\%$



Captured with PAV100 stabilised sensor



Captured without PAV100 stabilised sensor

Revolutionising the world of measurement and survey for nearly 200 years, Leica Geosystems creates complete solutions for professionals across the planet. Known for premium products and innovative solution development, professionals in a diverse mix of industries, such as surveying and engineering, safety and security, building and construction, and power and plant, trust Leica Geosystems to capture, analyse and present smart geospatial data. With the highest-quality instruments, sophisticated software and trusted services, Leica Geosystems delivers value every day to those shaping the future of our world.

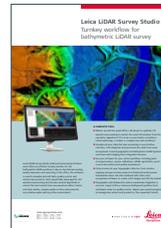
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**Leica Chiroptera-5**  
Highest bathymetric efficiency



**Leica LiDAR Survey Studio**  
Turnkey workflow



**Airborne Bathymetric LiDAR Solutions**  
Proven productivity

**Leica Geosystems AG**  
leica-geosystems.com



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